

REPUBLIQUE ALGERIENNE DEMOCRATIQUE ET POPULAIRE  
MINISTERE DE L'ENSEIGNEMENT SUPERIEUR ET DE LA RECHERCHE  
SCIENTIFIQUE

Université Abdelhamid Ibn Badis Mostaganem  
Laboratoire de Mathématiques Pures et Appliquées

*1<sup>ier</sup> Workshop*

*en*

*Contrôle et Optimisation*

*Mostaganem 18-19 et 20 Décembre 2011*

Global convergence of a modified hybrid **DY** and **HS** conjugate gradient method for non convex optimization

M.Belloufi, R.Benzine

mbelloufi@yahoo.fr, rabenzine@yahoo.fr

Les mots clés : unconstrained optimization, conjugate gradient method, line search, Sufficient descent condition

Résumé :The conjugate gradient method is a useful and powerful approach for solving large-scale minimization problems. Dai and Yuan developed a conjugate gradient method, which has good numerical performance and global convergence result under line searches such as Wolfe and strong Wolfe line search .Recently, we propose a modification of the Dai–Yuan conjugate gradient algorithm, which produces a descent search direction at every iteration and converges globally provided that the line search satisfies the weak Wolfe conditions.

## 0.1 Main results

Consider an unconstrained minimization problem

$$\min f(x), \quad x \in \mathbb{R}^n, \quad (1)$$

where  $\mathbb{R}^n$  denotes an n-dimensional Euclidean space and

$f : \mathbb{R}^n \rightarrow \mathbb{R}$  is a continuously differentiable function

Generally, a line search method takes the form

$$x_{k+1} = x_k + \alpha_k d_k, \quad k = 0, 1, 2, \dots$$

where  $d_k$  is a descent direction of  $f(x)$  at  $x_k$  and  $\alpha_k$  is a

step size. For convenience, we denote  $\nabla f(x_k)$  by  $g_k$ ,

The search direction  $d_k$  is generally required to satisfy

$$g_k^T d_k < 0,$$

which guarantees that  $d_k$  is a descent direction of  $f(x)$  at  $x_k$  [1].

In order to guarantee the global convergence, we sometimes

require  $d_k$  to satisfy a sufficient descent condition

$$g_k^T d_k \leq -c \|g_k\|^2,$$

where  $c > 0$  is a constant.

In line search methods, the well-known conjugate gradient method has the form (2) in which-

$$d_k = \begin{cases} -g_k, & \text{if } k = 0; \\ -g_k + \beta_k d_{k-1}, & \text{if } k \geq 1, \end{cases}$$

$$\text{where } \beta_k^{FR} = \frac{\|g_k\|^2}{\|g_{k-1}\|^2}, \quad \beta_k^{PRP} = \frac{g_k^T(g_k - g_{k-1})}{\|g_{k-1}\|^2}, \quad \beta_k^{HS} = \frac{g_k^T(g_k - g_{k-1})}{d_{k-1}^T(g_k - g_{k-1})}, \quad \beta_k^{DY} = \frac{\|g_k\|^2}{d_{k-1}^T g_{k-1}},$$

One often requires the inexact line search

such as the Wolfe conditions or the strong Wolfe conditions. The Wolfe

line search is to find  $\alpha_k$  such that

$$f(x_k + \alpha d_k) \leq f(x_k) + \rho \alpha \nabla^T f(x_k) d_k$$

$$\nabla^T f(x_k + \alpha d_k) d_k \geq \sigma \nabla^T f(x_k) d_k \quad \text{with } 0 < \rho < \sigma < 1,$$

Al-Baali [10] has proved the global convergence of the **FR** method for nonconvex functions with the strong Wolfe line search if the parameter  $\sigma < \frac{1}{2}$ . The **PRP** method with exact line search may cycle without approaching any stationary point, see Powell's counter-example [11]. Although one would be satisfied with its global convergence properties, the **FR** method sometimes performs much worse than the **PRP** method in real computations. A similar case happen to the **DY** method and the **HS** method. To combine the good numerical performance of the **PRP** and **HS** methods and the nice global convergence properties of the **FR** and **DY** methods, Touati-Ahmed and Storey [12] proposed a hybrid **PRP-FR** method which we call the **H1** method, that is,

$$\beta_k^{H1} = \max \{0, \min \{\beta_k^{PRP}, \beta_k^{FR}\}\}$$

Gilbert and Nocedal [13] extended this result to the case that

$$\beta_k = \max \{-\beta_k^{FR}, \min \{\beta_k^{PRP}, \beta_k^{FR}\}\}$$

## References

- [1] Y. Yuan, Numerical Methods for Nonlinear Programming, Shanghai Scientific & Technical Publishers, 1993.
- [2] R. Fletcher, C. Reeves, Function minimization by conjugate gradients, Comput. J. 7 (1964) 149–154.
- [3] E. Polak, G. Ribière, Note sur la convergence de directions conjuguées, Rev. Francaise Infomat Recherche Operatonelle, 3eAnnée 16 (1969) 35–43.
- [4] B.T. Polyak, The conjugate gradient method in extreme problems, USSR Comput. Math. Math. Phys. 9 (1969) 94–112.